

CRX-10iA



Max. load capacity at wrist: 10 kg



Max. reach: 1249 mm

FANUC

| Robot | | | Max. load capacity at wrist (kg) | Reach (mm) | Controlled axes | Repeatability (mm) | Mechanical weight (kg) | Motion range (°) | | | | | | Maximum speed (°/s) | | | | | | Allowable Wrist Load | | | Protection | | |
|--------|---------|------|----------------------------------|------------|-----------------|--------------------|------------------------|------------------|-----|-----|-----|-----|-----|---------------------|-----|-----|-----|-----|-----|----------------------|--------------------|--------------------|--------------------------|---------------|----------------|
| Series | Version | Type | | | | | | J1 | J2 | J3 | J4 | J5 | J6 | J1 | J2 | J3 | J4 | J5 | J6 | J4 Moment/ Inertia | J5 Moment/ Inertia | J6 Moment/ Inertia | Input power source (VAC) | Body standard | Wrist & J3 arm |
| CRX | iA | 10 | 10 | 1249 | 6 | ±0.04 | 39 | 380 | 360 | 570 | 380 | 360 | 380 | 120 | 120 | 180 | 180 | 180 | 180 | 34.8/ 1.28 | 26/ 0.9 | 11/ 0.3 | 100-120 200-240 | IP67 | IP67 |

● standard ○ on request - not available * max. cartesian speed 1000mm/sec ** Based on ISO9283 ***Option

CRX-10iA Standard model



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